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## Course Description

### Steel Framed Stairway Design

Part 2: Seismic Loads & Delegated Design

June 6, 2018

This session provides information regarding code requirements for seismic loading and serviceability criteria, guard/handrail design, design examples, considerations related to construction tolerances, additional design considerations, and delegated design.



## Learning Objectives

- Describe how seismic loads are combined with gravity loads in steel stair design.
- Select details that might be used to allow for stair movement during seismic events.
- Identify the items to be included in design documents when delegating the structural design of steel stairs.
- List tolerances to be accounted for at the interface between steel stairs and concrete or masonry elements.



## Steel Framed Stairway Design



Presented by  
Adam Friedman  
CSD Structural Engineers  
Milwaukee, WI



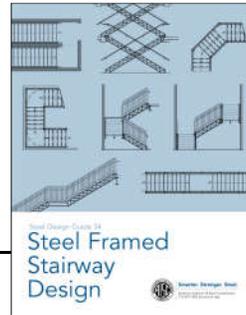
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## Introduction

### AISC Design Guide 34: Steel Framed Stairway Design

*to be published late summer / fall*

will be available at  
[www.aisc.org/designguides](http://www.aisc.org/designguides)  
free download for members or  
available for purchase



9

## Outline – Part 1 Recap

Step 1 – Purpose & Design Philosophy

Step 2 – Stairway Overview

Step 3 – Code Requirements - Gravity

Step 4 – Stairway Design

Step 5 – Members & Connx

Step 6 – Examples



10

## Outline – Part 2

Step 7 – Code Requirements – Seismic Loading

Step 8 – Seismic Serviceability

Step 9 – Stairway Design

Step 10 – Examples

Step 11 – Delegated Design

Step 12 – Other Topics



11

## Outline – Part 2

**Step 7 – Code Requirements – Seismic Loading**

Step 8 – Seismic Serviceability

Step 9 – Stairway Design

Step 10 – Examples

Step 11 – Delegated Design

Step 12 – Other Topics



12



## Applicable Codes

- International Building Code (IBC)
  - Chapter 16 “Structural Design” – Loads, Combos, & Serviceability
- ASCE/SEI 7-16 Minimum Design Loads for Buildings & Other Structures
  - Chapter 2 Combinations of Loads
  - Chapter 11 Seismic Design Criteria
  - Chapter 12 Seismic Design Criteria for Building Structures
  - Chapter 13 Seismic Design Criteria for Nonstructural Components



13

## Load Combinations

- Refer to ASCE7-16 Chapter 2 for LRFD & ASD Load Combinations

### LRFD

1. 1.4D
2. 1.2D+1.6L+0.5(Lr or S or R)
3. 1.2D+1.6(Lr or S or R)+1.0(L or 0.5W)
4. 1.2D+1.0W+1.0L+0.5(Lr or S or R)
5. 0.9D+1.0W
6. 1.2D+1.0Ev+1.0Eh+1.0L+0.2S
7. 0.9D-1.0Ev+1.0Eh

### ASD

1. D
2. D+L
3. D+(Lr or S or R)
4. D+0.75L+0.75(Lr or S or R)
5. D+0.6W
6. D+0.75L+0.75(0.6W)+0.75(Lr or S or R)
7. 0.6D+0.6W
8. D+0.7Ev+0.7Eh
9. D+0.525Ev+0.525Eh+0.75L+0.75S
10. 0.6D-0.7Ev+0.7Eh



14

## Loading – ASCE 7-16

- General Structural Integrity, Section 1.4.2 (SDC = A)
  - $F_x=0.01W_x$  (1.4-1)
- Seismic Loads (SDC = B, C, D, E, F)
  - Seismic Design Criteria (i.e.  $S_{DS}$ ) per Chapter 11 or from SER General Notes drawing
    - $S_{DS}$  = spectral acceleration, short period
  - Stairs to be designed per Chapter 13 for Nonstructural Components



15

## Loading – ASCE 7-16

- Horizontal Seismic Design Force, Eq. 13.3-1

$$F_p = \frac{0.4a_p S_{DS} W_p}{\left(\frac{R_p}{I_p}\right)} \left(1 + 2\frac{z}{h}\right)$$

$F_p$  = horizontal seismic design force at component center of gravity

•  $I_p$  = component importance factor per Section 13.1.3

Refer to Table 13.5-1

•  $a_p$  = component amplification factor

•  $R_p$  = component response modification factor



16



## Loading – ASCE 7-16, Table 13.5-1

TABLE 13.5-1 Coefficients for Architectural Components

Architectural Component	$a_p^a$	$R_p^b$	$\Omega_0^c$
Egress stairways not part of the building structure seismic force-resisting system	1	2 ½	2-½-2
Egress stairs and ramp fasteners and attachments	2 ½	2 ½	2 ½

Previously (ASCE 7-10):

$$a_p = 1, R_p = 2\frac{1}{2}, \Omega_0 = 2\frac{1}{2}$$

$a_p$  = component amplification factor

$R_p$  = component response modification factor

$\Omega_0$  = overstrength factor for anchorage to concrete & masonry



17

## Loading – ASCE 7-16, Table 13.5-1

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$\Omega_0$  = overstrength factor for anchorage to concrete & masonry



18

## Loading – ASCE 7-16, Table 13.5-1

- Multiple design criteria

- Design of members and connection material:

- $a_p=1.0, R_p=2.5$

- Design of fasteners/attachment (bolts/welds):

- $a_p=2.5, R_p=2.5$  (250% increase in forces from 2010)



19

## Loading – ASCE 7-16, Table 13.5-1

- Design of fasteners/attachment (anchors, embeds) in concrete/masonry:

- $\Omega_0 = 2.5$  (250% increase in forces from 2010 due to  $a_p = 2.5$ )

- Or ductile yielding of support/component

- Design of concrete/masonry member:

- $\Omega_0 = 2.0$  (20% reduction in forces from 2010)

- Or ductile yielding of support/component



20

## Loading – ASCE 7-16

- Horizontal Seismic Design Force, Eq. 13.3-1

$$F_p = \frac{0.4a_p S_{DS} W_p}{\left(\frac{R_p}{I_p}\right)} \left(1 + 2\frac{z}{h}\right)$$

For stair members:

- $I_p = 1.5$
- Refer to Table 13.5-1
- $a_p = 1.0$
- $R_p = 2.5$



21

## Loading – ASCE 7-16

- Horizontal Seismic Design Force, Eq. 13.3-1

$$F_{p, \text{stairs}} = 0.24 S_{DS} W_p \left(1 + 2\frac{z}{h}\right)$$

$S_{DS}$  = short period spectral acceleration

$W_p$  = component weight (dead load only)

$z$  = component height from grade at point of attachment

$h$  = average roof height

( $z/h$ ) may conservatively be taken as 1.0



22

## Loading – ASCE 7-16

- Horizontal Seismic Design Force
  - Minimum per Eq. 13.3-3

$$F_{p, \text{min}} = 0.3 S_{DS} I_p W_p$$

- Maximum per Eq. 13.3-2

$$F_{p, \text{max}} = 1.6 S_{DS} I_p W_p$$



23

## Loading – ASCE 7-16

- Horizontal Seismic Design Force for Stairs
  - If  $I_p=1.5$  and  $(z/h)=1.0$

$$F_{p, \text{stairs, min}} = 0.45 S_{DS} W_p$$

$$F_{p, \text{stairs}} = 0.72 S_{DS} W_p$$

$$F_{p, \text{stairs, max}} = 2.4 S_{DS} W_p$$



24

## Loading – ASCE 7-16

- Vertical Seismic Design Force per Section 13.3.1.2  

$$F_{pv} = \pm 0.2 S_{DS} W_p$$

### Seismic Load Combos

Refer to Sections 2.3.6 LRFD, 2.4.5 ASD, & 12.4.2.1/12.4.2.2 for combinations with  $F_{pv}$

<b>LRFD</b>	<b>ASD</b>
6. $1.2D + 0.2S_{DS}D + Q_E + L + 0.2S$	8. $1.0D + 0.7(0.2S_{DS})D + 0.7Q_E$
7. $0.9 - 0.2S_{DS}D + Q_E$	9. $1.0D + 0.525(0.2S_{DS})D + 0.75L + 0.525Q_E + 0.75S$
	10. $0.6D - 0.7(0.2S_{DS})D + 0.7Q_E$

Apply to dead load only



25

## Seismic Load Combos - Anchorage

- Refer to Sections 2.3.6 LRFD, 2.4.5 ASD, & 12.4.3/12.4.3.1 for combinations with overstrength factor  $\Omega_0$
- Use for design of anchors at concrete/masonry
- $\Omega_0 = 2.0$  to  $2.5$  (SDC = B\*, C, D, E, F) \* $\Omega_0 = 1.0$  for SDC B for concrete per ACI 318-14 section 17.2.3.1

<b>LRFD</b>	<b>ASD</b>
6. $1.2D + 0.2S_{DS}D + \Omega_0 Q_E + L + 0.2S$	8. $1.0D + 0.7(0.2S_{DS})D + 0.7\Omega_0 Q_E$
7. $0.9D - 0.2S_{DS}D + \Omega_0 Q_E$	9. $1.0D + 0.525(0.2S_{DS})D + 0.75L + 0.525\Omega_0 Q_E + 0.75S$
	10. $0.6D - 0.7(0.2S_{DS})D + 0.7\Omega_0 Q_E$

Apply  $\Omega_0$  to seismic portion of load only



26

## Outline – Part 2

Step 7 – Code Requirements – Seismic Loading

Step 8 – Seismic Serviceability

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Step 10 – Examples

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Step 12 – Other Topics



27

## Seismic Serviceability – ASCE 7-16

- Section 13.5.10 Egress Stairs & Ramps
  - Shall accommodate seismic displacement,  $D_{pl}$ 
    - Occur in any horizontal direction
    - Positive attachment
    - Direct structural supports or mechanical connections
  - Not part of seismic force-resisting system of structure



28

## Seismic Serviceability – ASCE 7-16

- Accommodate seismic displacement,  $D_{pl}$ 
  - Direct structural supports or mechanical connections with following requirements:
    - A. Sliding connx with holes, keepers, or stops
      - $D_{pl}$  or ½" minimum
      - Without loss of vertical support
      - Without inducing compression



29

## Seismic Serviceability – ASCE 7-16

- B. Bearing style details
  - $1.5D_{pl}$  or 1" minimum
  - Without loss of vertical support
- C. Metal supports with rotation capacity
  - $1.5D_{pl}$  or 1" minimum
  - Without loss of vertical support
  - No brittle failure modes
- D. Fasteners and attachments
  - Design for  $R_p, a_p, \Omega_0$  per table 13.5-1



30

## Seismic Serviceability – ASCE 7-16

### EXCEPTION:

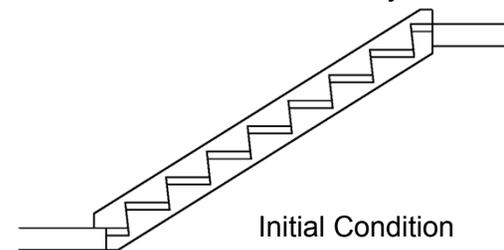
- If sliding or ductile connections not provided then stair **must be designed in the building structural model** and designed for  $\Omega_0$  of structure, but minimum 2.5.



31

## Serviceability – ASCE7-16 Section 13.3.2

- Seismic Displacement=Differential lateral movements between adjacent floors



32

### Seismic Displacement – ASCE 7-16

Differential movement may cause combination of compression/tension, bending, torsion, etc. depending on direction of movement.

Level x  
Level y  
 $\delta_y = 0$   
 $\delta_p = D_{pI}$   
 $h_{sx}$   
During Seismic Event

33

### Seismic Displacement – ASCE 7-16

- Stairs may provide inadvertent load path which braces building structure instead of seismic force resisting system (SFRS)

Stair stringers and connections will resist seismic forces instead of SFRS.

34

### Seismic Displacement – ASCE 7-16

- Some damage is acceptable, as long as other performance goals are not jeopardized (i.e. life safety for egress stairs). Refer to ASCE 7-16 commentary.

35

### Seismic Displacement – ASCE 7-16

- Refer to Section 13.3.2 Seismic Relative Displacements & Displacements within Structures 13.3.2.1

$$D_{pI} = D_p I_e \quad (\text{Eq 13.3-6})$$

$I_e$  = importance factor in Section 11.5.1 & Table 1.5-2

$$D_p = \delta_{xA} - \delta_{yA} \quad (\text{Eq 13.3-7})$$

$\delta$  = deflection in building at x or y level

- For delegated design, request SER provide accurate drift values for each floor level at each stairway**

36

## Seismic Displacement – ASCE 7-16

- Alternatively, ASCE 7 equation 13.3-8 & Table 12.12-1

$$D_{p, \max} = \frac{(h_x - h_y) \Delta_{aA}}{h_{sx}} = \frac{(h_x - h_y)(x h_{sx})}{h_{sx}} = (h_x - h_y)(x)$$

- $h_x$  = height of level x
- $h_y$  = height of level y
- $h_{sx}$  = story height
- $\Delta_{aA}$  = allowable story drift
- $\Delta_{aA} = x h_{sx}$  (Table 12.12-1)
- $x$  = constant per Structure & Risk Category
- $D_{p, \max}$  will result in large values that may be very difficult and costly to accommodate
- Designers can also use a linear dynamic procedure to determine  $D_p$  per Section 12.9.



37

## Seismic Displacement – ASCE 7-16

- How to accommodate seismic displacement?
  - Drift Details
  - Expansion joint or expansion gap
  - Connections / supports with rotation capacity
  - Design for imparted forces



38

## Seismic Displacement – ASCE 7-16

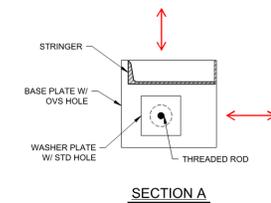
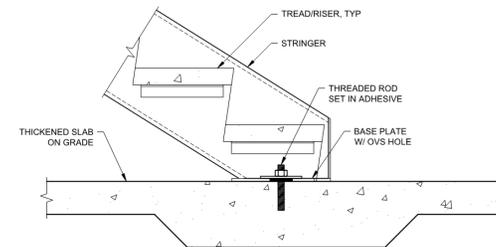
- Drift Details
  - Provide end connections allowing movement or drift at one end of stairway flight.
  - Other end connections must provide load path to resist lateral forces.
  - Use bearing for vertical loads.
  - Follow section 13.10.5 criteria A or B



39

## Seismic Displacement – ASCE 7-16

- Drift Detail at Slab on Grade



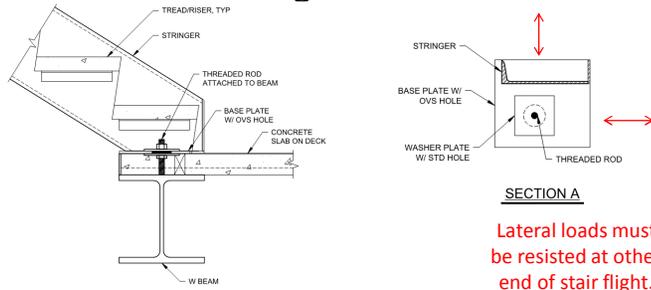
Lateral loads must be resisted at other end of stair flight.



40

## Seismic Displacement – ASCE 7-16

- Drift Detail at Wide Flange Beam



41

## Seismic Displacement – ASCE 7-16

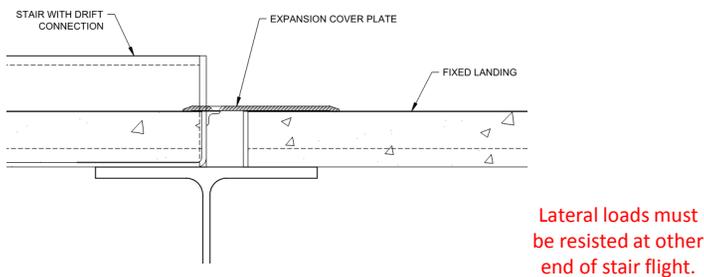
- Expansion joint or expansion cover
  - Likely requires input/approval from Architect
  - Provide gap allowing movement at one end of stairway flight.
  - Other end connections must provide load path to resist lateral forces.
  - Use bearing for vertical loads.
  - Follow section 13.10.5 criteria A or B



42

## Seismic Displacement – ASCE 7-16

- Expansion joint or expansion cover



43

## Seismic Displacement – ASCE 7-16

- Connections / supports with rotation capacity
  - Moment frame designed for imparted seismic displacement
  - Connections (that are part of a system) allowing for lateral displacement through the use of slotted/oversized holes or ductile elements
  - Requires careful detailing and analysis to ensure intended performance for seismic event



44

## Seismic Displacement – ASCE 7-16

- Design for imparted forces...  
...but remember:

$$\delta = \frac{PL}{AE} \therefore P = \frac{\delta AE}{L}$$

...likely results in very large forces.

- Needs to be part of building model for this analysis!



45

## Outline – Part 2

Step 7 – Code Requirements – Seismic Loading

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Step 11 – Delegated Design

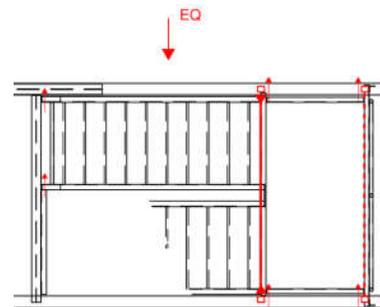
Step 12 – Other Topics



46

## Horizontal Load Path

- How do we analyze stair flight?
- How are forces transferred through landings?



47

## Stair Flight Assembly

- Load path for seismic forces on stair flight?
  - Option 1 – Individual Simple Span Members
  - Option 2 – Built-up Horizontal Beam
  - Option 3 – Cantilever Built-up Horizontal Beam
- Alternative options using engineering judgment



48

### Stair Flight Assembly

- Option 1 – Individual Simple Span Members

49

### Stair Flight Assembly

- Option 1 – Individual Simple Span Members
  - Assumes ductile connx or rotation capacity at supports
  - Treat as a simple span beam with uniformly distributed load
  - Design per AISC Spec

50

### Stair Flight Assembly

- Option 2 – Built-up Horizontal Beam

51

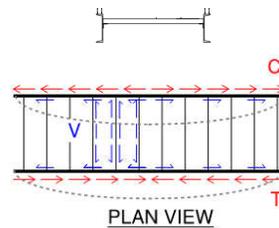
### Stair Flight Assembly

- Option 2 – Built-up Horizontal Beam
  - Assumes ductile connx or rotation capacity at supports
  - Built-up beam may not satisfy local buckling criteria at treads/risers in many cases (AISC, AISI)
  - Difficult to quantify capacity of tread/riser elements

52

## Stair Flight Assembly

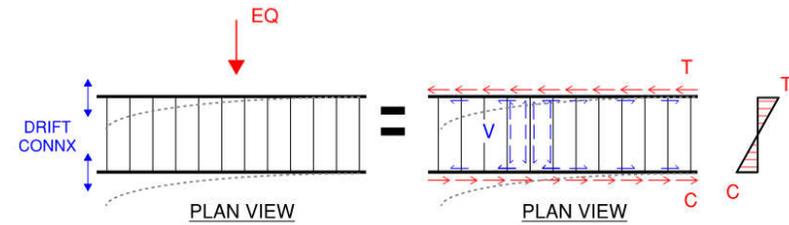
- Option 2 – Built-up Horizontal Beam



53

## Stair Flight Assembly

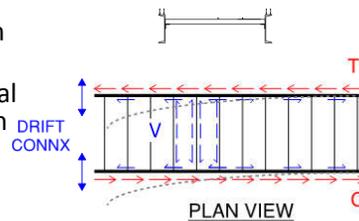
- Option 3 – Cantilever Built-up Horizontal Beam



54

## Stair Flight Assembly

- Option 3 – Cantilever Built-up Horizontal Beam
  - Assumes drift connx at one end
  - Force couple at opposite end with axial and weak axis connx forces
  - Built-up beam may not satisfy local buckling criteria at treads/risers in many cases (AISC, AISI)
  - Difficult to quantify capacity of tread/riser elements



55

## Landing Diaphragm

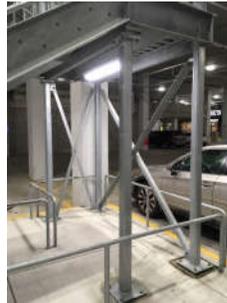
- Load path is more similar to conventional floor framing
  - Cast-in-place concrete over metal deck
    - Deck capacity / concrete capacity
  - Cast-in-place concrete over stiffened plate
  - Steel plate diaphragm



56

## Vertical Load Path

- Best systems for stairs?
- Least impact on
  - Aesthetics
  - Space constraints
  - Cost



57

## Vertical Lateral Load Resisting Systems

Type	Advantages	Disadvantages
Tension Only Bracing	<ul style="list-style-type: none"> <li>• Smaller member sizes</li> <li>• Can be concealed in walls</li> <li>• Can fit under landings</li> </ul>	<ul style="list-style-type: none"> <li>• Will require more members and more connections</li> </ul>
Tension-Compression Bracing	<ul style="list-style-type: none"> <li>• Less members</li> <li>• Less connections</li> <li>• Can be concealed in walls</li> <li>• Can fit under landings</li> </ul>	<ul style="list-style-type: none"> <li>• Members may be heavier and larger</li> <li>• Splices at member intersections are needed</li> </ul>
Moment Frames	<ul style="list-style-type: none"> <li>• Members do not cross path of travel (if required)</li> <li>• Can be concealed in walls</li> <li>• Beam member can also act as landing support member</li> </ul>	<ul style="list-style-type: none"> <li>• More lateral drift than other options</li> <li>• Connections typically more complex and more expensive</li> </ul>



58

## Outline – Part 2

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59

## Example 1: Load Determination

### Given:

- OSHA Style Industrial Stair
- Location: Southern California
- Seismic Design Category = D
- Spectral Response,  $S_{DS} = 0.660g$



60

### Example 1: Load Determination

**PLAN**

**SECTION**

61

### Example 1: Load Determination

- Load Combinations, ASCE7-16, 2.3.1 & 2.4.1

LRFD	ASD
≥ 1.2D + 1.6L	D+L ≥

62

### Example 1: Load Determination

- Load Combinations, ASCE7-16, 2.3.6 & 2.4.5

	LRFD	ASD
<u>6</u>	$1.2D + E_c + E_k + L + 0.2S$ $= 1.2D + 0.2S_{DS}D + \rho Q_E + L$ $= 1.2D + 0.2(0.660)D + 1.0Q_E + L$ $= 1.33D + 1.0Q_E + L$	<u>8</u>
<u>7</u>	$0.9D - E_c + E_k$ $= 0.9D - 0.2S_{DS}D + \rho Q_E$ $= 0.9D - 0.2(0.660)D + 1.0Q_E$ $= 0.768D + 1.0Q_E$	<u>9</u>
	$1.0D + 0.525E_c + 0.525E_k + 0.75L + 0.75S$ $= 1.0D + 0.525(0.2S_{DS})D + 0.525\rho Q_E + 0.75L$ $= 1.0D + 0.525((0.2)(0.660))D + 0.525(1.0)Q_E + 0.75L$ $= 1.07D + 0.525Q_E + 0.75L$	<u>10</u>
	$0.6D - 0.7E_c + 0.7E_k$ $= 0.6D - 0.7(0.2S_{DS})D + 0.7\rho Q_E$ $= 0.6D - 0.7(0.2)(0.660)D + 0.7(1.0)Q_E$ $= 0.508D + 0.7Q_E$	

63

### Example 1: Load Determination

- Horizontal Seismic Force,  $F_p$

$$F_p = \frac{0.4a_p S_{DS} w_p}{\left(\frac{R_p}{I_p}\right)} \left(1 + 2\frac{z}{h}\right)$$

where

$I_p$ = component importance factor from ASCE/SEI 7, Section 13.1.3	= 1.5
$R_p$ = component response modification factor from ASCE/SEI 7, Table 13.5-1	= 2.5
$S_{DS}$ = spectral acceleration, short period, determined from ASCE/SEI 7, Section 11.4.5	= 0.660g
$a_p$ = component amplification factor from ASCE/SEI 7, Table 13.5-1	= 1.0
$h$ = average roof height of structure with respect to base	= 19.8 ft
$z$ = height in structure of point of attachment of component with respect to base	= 9.92 ft

64

### Example 1: Load Determination

- Horizontal Seismic Force,  $F_p$

$$F_p = \frac{0.4(1.0)(0.660)W_p}{\left(\frac{2.5}{1.5}\right)} \left[ 1 + 2 \left( \frac{9.92 \text{ ft}}{19.8 \text{ ft}} \right) \right]$$

$$= 0.317W_p$$



65

### Example 1: Load Determination

- Maximum Horizontal Seismic Force,  $F_p \text{ max}$

$$F_p \text{ max} = 1.6S_{DS}I_pW_p$$

$$= 1.6(0.660)(1.5)W_p$$

$$= 1.58W_p$$

- Minimum Horizontal Seismic Force,  $F_p \text{ min}$

$$F_p \text{ min} = 0.3S_{DS}I_pW_p$$

$$= 0.3(0.660)(1.5)W_p$$

$$= 0.297W_p$$



66

### Example 1: Load Determination

- Vertical Seismic Force,  $F_{pv}$

$$F_{pv} = \pm 0.2S_{DS}W_p$$

$$= \pm 0.2(0.660)W_p$$

$$= \pm 0.132W_p$$



67

### Example 1: Load Determination

- Summary

– Horizontal

$$F_p = 0.317W_p$$

– Vertical

$$F_{pv} = \pm 0.132W_p$$

Remember, this is built  
 into load combinations



68



## Example 2: Stringer Design

### Given:

- OSHA Style Industrial Stair
- Location: Southern California
- Seismic Design Category = D
- Spectral Response,  $S_{DS} = 0.660g$
- Provide HSS A500 Gr. C Stringer



69

## Example 2: Stringer Design

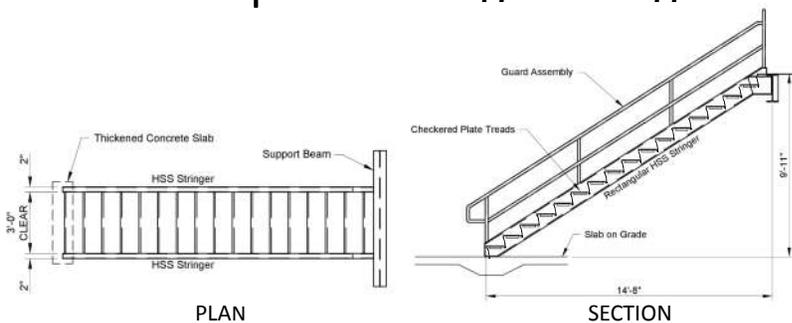
### Given:

- Supports with rotation capacity to accommodate seismic displacement using ductile connections
- Checkered plate tread/risers
  - Stringer fully braced
  - For seismic lateral loads, design as individual members



70

## Example 2: Stringer Design



71

## Example 2: Stringer Design

### Imposed Gravity Loading

Dead Load:

Stringer Self weight, HSS12x2x1/4		
Guard Self weight		
3/16" Checkered Plate	=	10 psf
Total	=	10 psf

Live Load:

Live load – Case 1	=	60 psf
Or		
Live load – Case 2	=	1000 lbs



72

## Example 2: Stringer Design

- Stringer Gravity Uniform Loads

Dead Load:			
Stringer Self weight (22.42 lb/ft X 1.19 slope factor)	=	26.7	lb/ft
Guard Self weight (20 lb/ft)	=	20	lb/ft
3/16" Checkered Plate = 10 psf X 1.5'	=	15	lb/ft
<b>Total</b>	<b>=</b>	<b>61.7</b>	<b>lb/ft</b>
Live Load:			
Live load = 60 psf X 1.5'	=	90	lb/ft
<b>Total</b>	<b>=</b>	<b>90</b>	<b>lb/ft</b>



73

## Example 2: Stringer Design

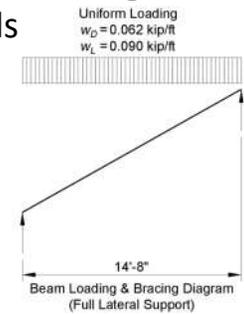
- Stringer Gravity Uniform Loads

$$w_D = \left(\frac{3 \text{ ft}}{2}\right)(0.010 \text{ kip/ft}^2) + (0.0267 \text{ kip/ft} + 0.020 \text{ kip/ft})$$

$$= 0.0617 \text{ kip/ft}$$

$$w_L = \left(\frac{3 \text{ ft}}{2}\right)(0.060 \text{ kip/ft}^2)$$

$$= 0.090 \text{ kip/ft}$$



74

## Example 2: Stringer Design

LRFD	ASD
<i>Uniform loading</i>	<i>Uniform loading</i>
$w_u = \left(\frac{3 \text{ ft}}{2}\right)[1.2(0.010 \text{ kip/ft}^2) + 1.6(0.060 \text{ kip/ft}^2)]$	$w_u = \left(\frac{3 \text{ ft}}{2}\right)[(0.010 \text{ kip/ft}^2) + (0.060 \text{ kip/ft}^2)]$
$+ 1.2(0.0267 \text{ kip/ft} + 0.020 \text{ kip/ft})$	$+ (0.0267 \text{ kip/ft} + 0.020 \text{ kip/ft})$
$= 0.218 \text{ kip/ft}$	$= 0.152 \text{ kip/ft}$
$V_u = \frac{14.7 \text{ ft}}{2}(0.218 \text{ kip/ft})$	$V_u = \frac{14.7 \text{ ft}}{2}(0.152 \text{ kip/ft})$
$= 1.60 \text{ kips}$	$= 1.12 \text{ kips}$
$M_u = \frac{(0.218 \text{ kip/ft})(14.7 \text{ ft})^2}{8}$	$M_u = \frac{(0.152 \text{ kip/ft})(14.7 \text{ ft})^2}{8}$
$= 5.89 \text{ kip-ft}$	$= 4.11 \text{ kip-ft}$



75

## Example 2: Stringer Design

- Stringer Point Load, 1000 lbs

*Point loading*

$$V_u = \frac{14.7 \text{ ft}}{2}[1.2(0.0617 \text{ kip/ft})] + 1.6(1 \text{ kip})$$

$$= 2.14 \text{ kips} \quad \text{GOVERNS}$$

$$M_u = \frac{1.2(0.0617 \text{ kip/ft})(14.7 \text{ ft})^2}{8}$$

$$+ \frac{1.6(1 \text{ kip})(14.7 \text{ ft})}{4}$$

$$= 7.88 \text{ kip-ft} \quad \text{GOVERNS}$$

*Point loading*

$$V_u = \frac{14.7 \text{ ft}}{2}(0.0617 \text{ kip/ft}) + 1 \text{ kip}$$

$$= 1.45 \text{ kips} \quad \text{GOVERNS}$$

$$M_u = \frac{(0.0617 \text{ kip/ft})(14.7 \text{ ft})^2}{8} + \frac{(1 \text{ kip})(14.7 \text{ ft})}{4}$$

$$= 5.34 \text{ kip-ft} \quad \text{GOVERNS}$$



76

## Example 2: Stringer Design

- Summary, Gravity Loads

	LRFD	ASD
w	0.218 k/ft	0.152 k/ft
V	2.14 k	1.45 k
M	7.88 k-ft	5.34 k-ft

Refer to *Specification* Section G1 & Manual Table 3-12

For HSS12x2x1/4 A500 Gr. C

LRFD

$$\Phi_v V_n = 142 \text{ k} > 2.14 \text{ k OK}$$

$$\Phi_b M_p = 75.4 \text{ k-ft} > 7.88 \text{ k-ft OK}$$

ASD

$$V_n / \Omega_v = 94.6 \text{ k} > 1.45 \text{ k OK}$$

$$M_p / \Omega_b = 50.1 \text{ k-ft} > 5.34 \text{ k-ft OK}$$

HSS12x2x1/4 is adequate for imposed gravity loads



77

## Example 2: Stringer Design

- Seismic Loading

– Consider equivalent uniform load for concentrated point load since it will govern design

$$P_L = 1 \text{ kip}$$

$$M = \frac{PL}{4} \quad \text{therefore...} \quad w_{Leq} = \frac{2P}{L}$$

$$= \frac{wL^2}{8} \quad = \frac{2(1 \text{ kip})}{14.7 \text{ ft}}$$

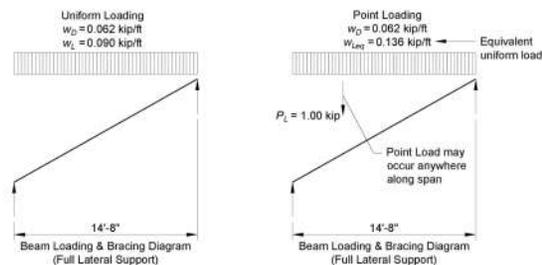
$$= 0.136 \text{ kip/ft}$$

$$w_{Leq} = 0.136 \text{ kip/ft} > w_L = 0.090 \text{ kip/ft}$$



78

## Example 2: Stringer Design



79

## Example 2: Stringer Design

- Stringer Vertical Loads, Seismic Load Combo

LRFD	ASD
$1.33D + 1.0Q_e + L$ (Controls for stringer design)	$1.07D + 0.525Q_e + 0.75L$ (Controls for stringer design)
$V_{u,v} = \left( \frac{14.7 \text{ ft}}{2} \right) \left[ \begin{matrix} 1.33(0.0617 \text{ kip/ft}) \\ +1.0(0) \\ + (0.136 \text{ kip/ft}) \end{matrix} \right]$ = 1.60 kips	$V_{a,v} = \left( \frac{14.7 \text{ ft}}{2} \right) \left[ \begin{matrix} 1.07(0.0617 \text{ kip/ft}) \\ +0.525(0) \\ +0.75(0.136 \text{ kip/ft}) \end{matrix} \right]$ = 1.23 kips
$M_{u,v} = \frac{(14.7 \text{ ft})^2}{8} \left[ \begin{matrix} 1.33(0.0617 \text{ kip/ft}) \\ +1.0(0) \\ + (0.136 \text{ kip/ft}) \end{matrix} \right]$ = 5.89 kip-ft	$M_{a,v} = \frac{(14.7 \text{ ft})^2}{8} \left[ \begin{matrix} 1.07(0.0617 \text{ kip/ft}) \\ +0.525(0) \\ +0.75(0.136 \text{ kip/ft}) \end{matrix} \right]$ = 4.54 kip-ft



80

## Example 2: Stringer Design

- Summary - Vertical Loads, Seismic Load Combo

	LRFD	ASD
w	0.218 k/ft	0.168 k/ft
V	1.60 k	1.23 k
M	5.89 k-ft	4.54 k-ft

Refer to *Specification* Section G1 & Manual Table 3-12

For HSS12x2x1/4 A500 Gr. C

LRFD

$\Phi_v V_n = 142 \text{ k} > 1.60 \text{ k}$  OK

$\Phi_b M_p = 75.4 \text{ k-ft} > 5.89 \text{ k-ft}$  OK

ASD

$V_n / \Omega_v = 94.6 \text{ k} > 1.23 \text{ k}$  OK

$M_p / \Omega_b = 50.1 \text{ k-ft} > 4.54 \text{ k-ft}$  OK

HSS12x2x1/4 is adequate for imposed vertical loads



81

## Example 2: Stringer Design

- Horizontal Loading

$$F_{ph} = 0.317W_p$$

$$= 0.317(0.062 \text{ kip/ft})$$

$$= 0.020 \text{ kip/ft}$$



82

## Example 2: Stringer Design

- Horizontal Loads, Seismic Load Combo

LRFD	ASD
$1.33D + 1.0Q_s + L$ (Controls for stringer design)	$1.07D + 0.525Q_s + 0.75L$ (Controls for stringer design)
$V_{a,b} = \left(\frac{14.7 \text{ ft}}{2}\right) [1.33(0) + 1.0(0.020 \text{ kip/ft}) + 0]$ = 0.147 kip	$V_{a,b} = \left(\frac{14.7 \text{ ft}}{2}\right) [1.07(0) + 0.525(0.020 \text{ kip/ft})]$ = 0.0772 kip
$M_{a,b} = \frac{(14.7 \text{ ft})^2}{8} [1.33(0) + 1.0(0.020 \text{ kip/ft}) + 0]$ = 0.540 kip-ft	$M_{a,b} = \frac{(14.7 \text{ ft})^2}{8} [1.07(0) + 0.525(0.020 \text{ kip/ft})]$ = 0.284 kip-ft



83

## Example 2: Stringer Design

- Summary - Horizontal Loads, Seismic Load Combo

	LRFD	ASD
w	0.020 k/ft	0.0105 k/ft
V	0.147 k	0.077 k
M	0.540 k-ft	0.284 k-ft

Refer to *Specification* Section G1 & Manual Table 3-12

For HSS12x2x1/4 A500 Gr. C

LRFD

$\Phi_v V_n = 16.4 \text{ k} > 0.147 \text{ k}$  OK

$\Phi_b M_p = 13.3 \text{ k-ft} > 0.540 \text{ k-ft}$  OK

ASD

$V_n / \Omega_v = 10.9 \text{ k} > 0.077 \text{ k}$  OK

$M_p / \Omega_b = 8.87 \text{ k-ft} > 0.284 \text{ k-ft}$  OK



84

## Example 2: Stringer Design

- Check Interaction
  - Because  $P_r/P_c < 0.2$ , use AISC *Specification* Equation H1-1b:

LRFD	ASD
$\frac{P_r}{2P_c} + \left( \frac{M_{rx}}{M_{cx}} + \frac{M_{ry}}{M_{cy}} \right) \leq 1.0$	$\frac{P_r}{2P_c} + \left( \frac{M_{rx}}{M_{cx}} + \frac{M_{ry}}{M_{cy}} \right) \leq 1.0$
$0 + \left( \frac{5.89 \text{ kip-ft}}{75.4 \text{ kip-ft}} + \frac{0.540 \text{ kip-ft}}{13.3 \text{ kip-ft}} \right) \leq 1.0$	$0 + \left( \frac{4.54 \text{ kip-ft}}{50.1 \text{ kip-ft}} + \frac{0.284 \text{ kip-ft}}{8.87 \text{ kip-ft}} \right) \leq 1.0$
0.119 < 1.0 <b>o.k.</b>	0.123 < 1.0 <b>o.k.</b>

HSS12x2x1/4 is adequate for seismic loads



85

## Example 2: Stringer Design

- Not quite done...
  - Consider seismic loads parallel to stair flight resulting in axial forces (and vertical loads)
  - Connection design
    - Remember that anchorage to concrete or masonry requires the use of load combinations with overstrength factor,  $\Omega_o$



86

## Outline – Part 2

Step 7 – Code Requirements – Seismic Loading

Step 8 – Seismic Serviceability

Step 9 – Stairway Design

Step 10 – Examples

Step 11 – Delegated Design

Step 12 – Other Topics



87

## Delegated Design

- Design Team (architect/SER) request contractor or fabricator to complete an aspect of design. For stairs:
  - Option 1 – Delegate all aspects of design
    - Contractor makes all design decisions with code input from design documents
  - Option 2 – Delegate structural engineering (*most common*)
    - Use design documents for architectural & code
  - Option 3 – Design-build
    - Use design documents and coordination with Design Team to establish parameters



88

## Delegated Design – Required Information

### Design Drawings

- Plans, sections, & elevations of each stair
  - Dimensions for clear distances at stairs/landings
  - Guard layout with handrail position
  - Preferred/required member types (C, HSS, Plate)
  - Slab openings
  - Conceptual layout of stair elements
  - Conceptual connection details
- Clearly indicate if details are suggestions or required



89

## Delegated Design – Required Information

### Project Specification

- Performance requirements (loading / serviceability)
  - Materials, member, & fasteners criteria
  - Fabrication instructions
  - Finishes
- Carefully review for conflicts between drawings and specification



90

## Delegated Design – Code Compliance

- Stairways, guard, and handrail are critical components related to life safety.
- Architect/SER are the most knowledgeable about the specific project requirements (and code requirements)
- Architect & SER are responsible for providing code parameters and reviewing submittals for conformance.



91

## Delegated Design

- Delegated Design ≠ “Not my problem”



92

## Delegated Design – Shop Drawings

- Shop drawings should be created by Fabricator/Detailer based on information provided by the specialty structural engineer (SSE) and design documents
- Provide shop drawings to SSE for review and comment
- Do not request SSE to seal shop drawings if they are created by others
  - Not allowed in some jurisdictions
  - Insurance typically will not allow SSE to do this



93

## Delegated Design – Submittals

- Submittal to Design Team & AHJ:
    - Shop & Erection drawings from Fabricator/Detailer
      - Reviewed by SSE
    - Sealed structural engineering calculations from specialty structural engineer (SSE)
      - Should include any plans, sketches, and details as required
- Be sure to clarify scope of work and expectations before submittals are made



94

## Outline – Part 2

Step 7 – Code Requirements – Seismic Loading

Step 8 – Seismic Serviceability

Step 9 – Stairway Design

Step 10 – Examples

Step 11 – Delegated Design

Step 12 – Other Topics



95

## Tolerances

- Steel
  - Mill Variations, ASTM A6 / AISC *COSP* Section 5.1
  - Fabrication Tolerances, AISC *COSP* Section 6.4
  - Erection Tolerances, AISC *COSP* Section 7.13
  - AESS, AISC *COSP* Sections 10.2-10.6



96



## Tolerances - Concrete



- Field verify dimensions based on actual construction!



97

## Tolerances

- Concrete (ACI117 & *Handbook of Construction Tolerances*)
  - $\pm 1/4$ " over 10 feet from plumb for walls
  - $\pm 1/4$ " to  $1/2$ " variation in distance between members
  - $+3/8$ " to  $-1/4$ " for cross sections
  - $+1$ " to  $-1/4$ " variation in floor openings
  - $\pm 1/2$ " member misplaced in plan
- Field verify dimensions based on actual construction!



98

## Tolerances

- Masonry (ASTM C90 & *Handbook of Construction Tolerances*)
  - $\pm 1/8$ " for cross sections
  - $\pm 1/4$ " to  $\pm 1/2$ " from plumb for walls
  - $\pm 1/2$ " alignment for bearing walls
- Field verify dimensions based on actual construction!



99

## Galvanizing

- For exterior locations or environments that need additional corrosion protection
- Consider:
  - Avoid field welding
  - Provide bolted connections
  - Match fasteners & metals
  - Limit on size of piece/assembly
  - Potential distortion or warpage (ASTM A384)



100

## Erectability

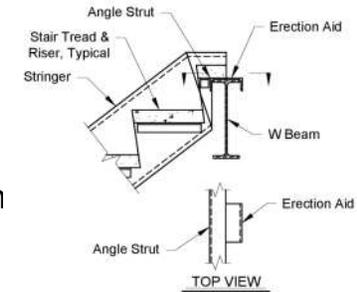
- Think about installation
  - Stringers adjacent to concrete/masonry walls may have limited access to install bolts
  - Will masonry supports be in place?
- Erector preferences
  - Bolting versus Welding



101

## Erectability

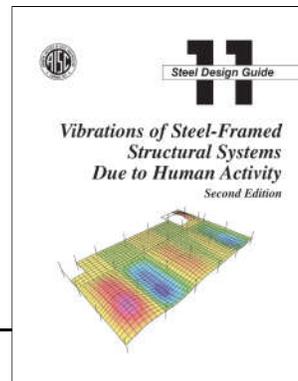
- Maximize repetition in framing and connections
- Erection aids
- Adjustability and fit-up in connections



102

## Vibration

- Refer to AISC Design Guide 11: Vibrations of Steel-Framed Structural Systems Due to Human Activity (Second Edition)
- Vibration is all about perception and comfort
- Discuss project goals as it relates to vibration



103

## Questions?



104

## PDH Certificates

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Within 2 business days...

- You will receive an email on how to report attendance from: [registration@aisc.org](mailto:registration@aisc.org).
- Be on the lookout: Check your spam filter! Check your junk folder!
- Completely fill out online form. Don't forget to check the boxes next to each attendee's name!



## PDH Certificates

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Within 2 business days...

- Reporting site (URL will be provided in the forthcoming email).
- Username: Same as AISC website username.
- Password: Same as AISC website password.



# Thank You

Please give us your feedback!  
*Survey at conclusion of webinar.*



There's always a solution in steel.

